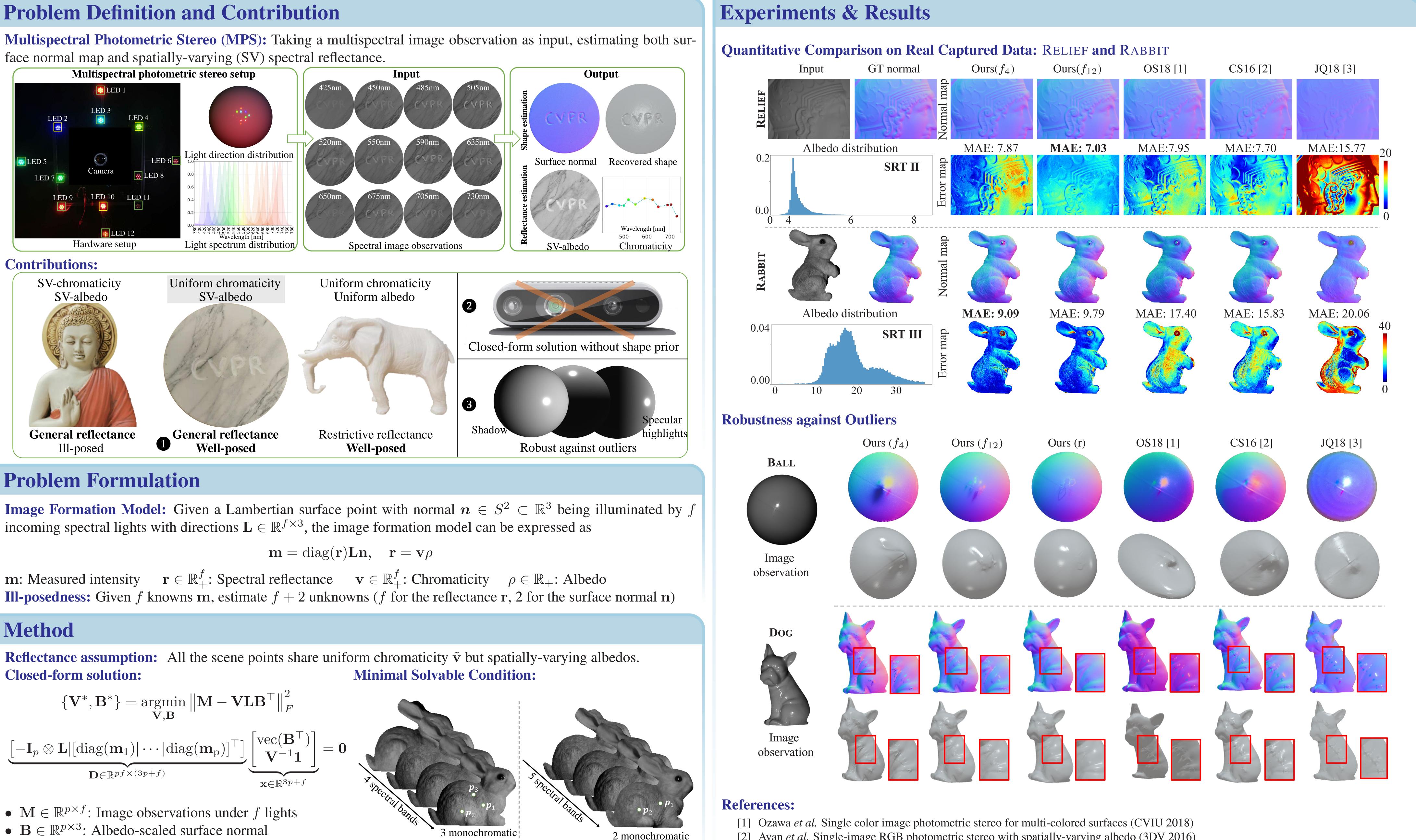


Multispectral Photometric Stereo for Spatially-Varying Spectral Reflectances: A well posed problem?

Problem Definition and Contribution



scene points

Closed-form solution:

$$\{\mathbf{V}^*, \mathbf{B}^*\} = \operatorname*{argmin}_{\mathbf{V}, \mathbf{B}} \left\|\mathbf{M} - \mathbf{V}\mathbf{L}\mathbf{B}^\top\right\|_F^2$$

$$\underbrace{\left[-\mathbf{I}_{p}\otimes\mathbf{L}|[\operatorname{diag}(\mathbf{m}_{1})|\cdots|\operatorname{diag}(\mathbf{m}_{p})]^{\top}\right]}_{\mathbf{D}\in\mathbb{R}^{pf\times(3p+f)}}\underbrace{\begin{bmatrix}\operatorname{vec}(\mathbf{B}^{\top})\\\mathbf{V}^{-1}\mathbf{1}\end{bmatrix}}_{\mathbf{x}\in\mathbb{R}^{3p+f}}=\mathbf{0}$$

- $\mathbf{M} \in \mathbb{R}^{p \times f}$: Image observations under f lights
- $\mathbf{B} \in \mathbb{R}^{p \times 3}$: Albedo-scaled surface normal
- $\mathbf{V} = \operatorname{diag}(\tilde{\mathbf{v}})$: Diagonalized uniform chromaticity $\tilde{\mathbf{v}}$

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scene points

[2] Ayan *et al.* Single-image RGB photometric stereo with spatially-varying albedo (3DV 2016) [3] Ju *et al.* Demultiplexing colored images for multispectral photometric stereo via deep neural networks (IEEE Access 2018)



